

Industrial Robot

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and

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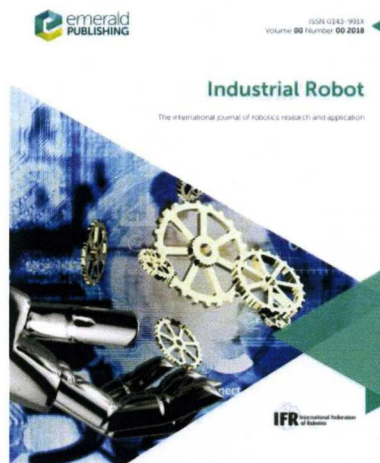
Highly Commended Paper

Awarded to:

Daisuke Chugo, Yao Li, Satoshi Muramatsu, Sho Yokota,
Jin-Hua She and Hiroshi Hashimoto

For the Paper:

*Assistive walker which stabilizes the user's posture and
prevent falls through abnormal gait pattern recognition*



Clive Loughlin
Editor

